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As was discussed in Chapter 7,
Luenberger observers often
exacerbate sensor-noise problems.
While some authors have described
uses of observers to reduce noise, in
many cases the observer will have the

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opposite effect. As discussed in Chapter 7, lowering observer bandwidth will reduce noise susceptibility, but it also reduces the ability of the observer to improve the system. For example ...

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End-of-chapter problems constitute a major component of this book and come in two basic varieties. The first consists of miscellaneous mathematical problems and proofs that extend and supplement the theoretical material in the text; the

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second, optimization problems, illustrates further areas of application and helps the reader formulate and solve practical problems. For professionals and ...

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A comprehensive introduction to the tools, techniques and applications of convex optimization.

Interactive Operations Research with Maple: Methods and Models has two

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course in operations research, management science, or quantitative methods. A number of students in the departments of operations research, management science, operations management, industrial and systems engineering, applied mathematics and advanced MBA students who are

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specializing in quantitative methods or operations management will find this text useful. Experienced researchers and practitioners of operations research who wish to acquire a quick overview of how Maple can be useful in solving OR problems will find this an excellent

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reference. Maple's mathematical knowledge base now includes calculus, linear algebra, ordinary and partial differential equations, number theory, logic, graph theory, combinatorics, statistics and transform methods. Although Maple's main strength lies in its ability to

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perform symbolic manipulations, it also has a substantial knowledge of a large number of numerical methods and can plot many different types of attractive-looking two-dimensional and three-dimensional graphs. After almost two decades of continuous improvement of its mathematical

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capabilities, Maple can now boast a user base of more than 300,000 academics, researchers and students in different areas of mathematics, science and engineering.

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fully revised and updated. It comprehensively covers modern theoretical insights in this crucial computing area, and will be required reading for analysts and operations researchers in a variety of fields. The book connects the purely analytical character of an optimization problem,

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and the behavior of algorithms used to solve it. Now, the third edition has been completely updated with recent Optimization Methods. The book also has a new co-author, Yinyu Ye of California ' s Stanford University, who has written lots of extra material including some on Interior Point

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Methods.

Multiplicative noise appears in systems where the process or measurement noise levels depend on the system state vector. Such systems are relevant, for example, in radar measurements where larger ranges

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involve higher noise level. This monograph embodies a comprehensive survey of the relevant literature with basic problems being formulated and solved by applying various techniques including game theory, linear matrix inequalities and Lyapunov parameter-dependent

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functions. Topics covered include:
convex H_2 and H -infinity norms
analysis of systems with multiplicative
noise; state feedback control and state
estimation of systems with
multiplicative noise; dynamic and
static output feedback of stochastic
bilinear systems; tracking controllers

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for stochastic bilinear systems utilizing preview information. Various examples which demonstrate the applicability of the theory to practical control engineering problems are considered; two such examples are taken from the aerospace and guidance control areas.

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This book presents a range of dynamic programming (DP) techniques applied to the optimization of dynamical systems.

As our title reveals, we focus on optimal control methods and

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applications relevant to linear dynamic economic systems in discrete-time variables. We deal only with discrete cases simply because economic data are available in discrete forms, hence realistic economic policies should be established in discrete-time structures.

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Though many books have been written on optimal control in engineering, we see few on discrete-type optimal control. More over, since economic models take slightly different forms than do engineering ones, we need a comprehensive, self-contained treatment of linear optimal

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control applicable to discrete-time economic systems. The present work is intended to fill this need from the standpoint of contemporary macroeconomic stabilization. The work is organized as follows. In Chapter 1 we demonstrate instrument instability in an economic

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stabilization problem and thereby establish the motivation for our departure into the optimal control world. Chapter 2 provides fundamental concepts and propositions for controlling linear deterministic discrete-time systems, together with some economic applica

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tions and numerical methods. Our optimal control rules are in the form of feedback from known state variables of the preceding period. When state variables are not observable or are accessible only with observation errors, we must obtain appropriate proxies for these

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variables, which are called "observers" in deterministic cases or "filters" in stochastic circumstances. In Chapters 3 and 4, respectively, Luenberger observers and Kalman filters are discussed, developed, and applied in various directions. Noticing that a separation principle lies between

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observer (or filter) and controller (cf.

Featuring contributions from leading experts, the Road and Off-Road Vehicle System Dynamics Handbook provides comprehensive, authoritative coverage of all the major issues involved in road vehicle dynamic

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behavior. While the focus is on automobiles, this book also highlights motorcycles, heavy commercial vehicles, and off-road vehicles. The authors of the individual chapters, both from automotive industry and universities, address basic issues, but also include references to significant

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papers for further reading. Thus the handbook is devoted both to the beginner, wishing to acquire basic knowledge on a specific topic, and to the experienced engineer or scientist, wishing to have up-to-date information on a particular subject. It can also be used as a textbook for

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master courses at universities. The handbook begins with a short history of road and off-road vehicle dynamics followed by detailed, state-of-the-art chapters on modeling, analysis and optimization in vehicle system dynamics, vehicle concepts and aerodynamics, pneumatic tires and

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contact wheel-road/off-road, modeling vehicle subsystems, vehicle dynamics and active safety, man-vehicle interaction, intelligent vehicle systems, and road accident reconstruction and passive safety. Provides extensive coverage of modeling, simulation, and analysis

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techniques Surveys all vehicle subsystems from a vehicle dynamics point of view Focuses on pneumatic tires and contact wheel-road/off-road Discusses intelligent vehicle systems technologies and active safety Considers safety factors and accident reconstruction procedures Includes

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chapters written by leading experts from all over the world This text provides an applicable source of information for all people interested in a deeper understanding of road vehicle dynamics and related problems.

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Experience gained during a ten-year long involvement in modelling, programming and application in nonlinear optimization helped me to arrive at the conclusion that in the interest of having successful applications and efficient software production, knowing the structure of

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the problem to be solved is in dispensable. This is the reason why I have chosen the field in question as the sphere of my research. Since in applications, mainly from among the nonconvex optimization models, the differentiable ones proved to be the most efficient in modelling, especially

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in solving them with computers, I started to deal with the structure of smooth optimization problems. The book, which is a result of more than a decade of research, can be equally useful for researchers and students showing interest in the domain, since the elementary notions necessary for

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understanding the book constitute a part of the university curriculum. I intended dealing with the key questions of optimization theory, which endeavour, obviously, cannot bear all the marks of completeness. What I consider the most crucial point is the uniform, differential geometric

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treatment of various questions, which provides the reader with opportunities for learning the structure in the wide range, within optimization problems. I am grateful to my family for affording me tranquil, productive circumstances. I express my gratitude to F.

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Justification of the state-contingent approach to the economics of uncertainty.

Convex optimization problems arise frequently in many different fields. This book provides a comprehensive

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introduction to the subject, and shows in detail how such problems can be solved numerically with great efficiency. The book begins with the basic elements of convex sets and functions, and then describes various classes of convex optimization problems. Duality and approximation

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techniques are then covered, as are statistical estimation techniques. Various geometrical problems are then presented, and there is detailed discussion of unconstrained and constrained minimization problems, and interior-point methods. The focus of the book is on recognizing convex

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optimization problems and then finding the most appropriate technique for solving them. It contains many worked examples and homework exercises and will appeal to students, researchers and practitioners in fields such as engineering, computer science,

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mathematics, statistics, finance and economics.

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